

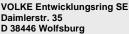
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## VOLKE Towing Dynamometer VBA08-2xx 125kW – 8kN



Maximum drawbar pull	8.000 N (limited by maximum power above 57 kph, cf. drawbar pull map, page 5)
Continuous drawbar pull	8.000 N up to 35 kph 4.800 N up to 60 kph 1.800 N up to 160 kph Detailed information in drawbar pull map (page 5)
Max/ continuous power	125 / 80 kW
Speed range	0 - 160 kph (max. speed on public road based on country-specific regulations) Limitation of operation speed is applicable by a password query
Continuous braking device	1 Air-cooled eddy current brake (ECB) with air ducts and additional electric fan to improve cooling capacity  Operated by thyristor-impulse-controller  Rev limiter: When reaching the ECB rev limit, dynamometer and remote control resound a warning tone
Transmission	Three-speed gearbox, manually shiftable at standstill - Neutral gear - 1 <sup>st</sup> gear (0 to 80 kph) - 2 <sup>nd</sup> gear (5 to 120 kph) - 3 <sup>rd</sup> gear (10 to 160 kph)  Optional: Axle gear oil-cooled
Drawbar pull measurement	Via linear roller-bearing-mounted towbar and HBM U2A load cell
Speed measurement	Via ABS wheel speed sensors (slip-dependent)
Public road approval	"100-kph-permission" for motor highways (Europe)  Option: Operating permission for public roads. Modified ballast weight and additional lighting needed. (1 <sup>st</sup> and 2 <sup>nd</sup> -gear use only)  This option is part of the option package. Operating permission carried out by the respective local approval body.



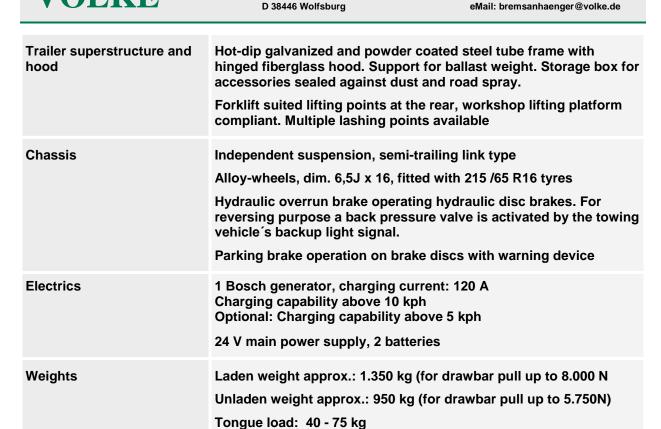
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Daimlerstr. 35

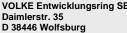
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**Outer dimensions** 





length: 4.200 mm width: 1.800 mm height: 1.100 mm (approx.)



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Control Waterproof (IP67) control unit, passive cooled Powerful, robust and modular control system( National Instruments), controller and FPGA Diagnosis functions and monitoring of various system parameters, e.g. battery voltage, ECB voltage and temperature, air temperature etc. Acoustic warnings during operation in case of unlocked hood, active parking brake or reaching ECB rev limit. Remote control 4,3" TFT LCD integrated in casing. Dimensions approx.: 200 x 11 x 65 mm (WxHxD) Menu based control via function buttons, push/turn control knob and an emergency shut-off button. User interface displays all current operation parameters and warnings. Communication between remote control and towing dynamometer via CAN-Bus, cable connection to remote control Ø approx.. 7 mm Additional CAN-Bus interface for data logging process parameters by remote control (e.g., drawbar pull, speed) **Externally supplied setpoint via CAN-Bus** Online help function with brief instruction, security advices etc. Available menu languages: english, german





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Control functions in **Drawbar pull control** standard configuration **Speed control** Anti-lock braking system (ABS) (If tyre slip exceedes threshold the drawbar pull is reduced for a short term) **Optional features** Remote control via wireless connection and interruption-free power-supply by the towing vehicle. Driver assistant display -Additional windscreen-mounted driver assistant display containing realtime operation parameters and driving hill profiles. Set point ramp for speed control In speed control mode a slew rate is integrated into the setpoint adjustment. CAN-data logger for logging operation parameters, also used for troubleshooting and support. CAN-analog-converter to display analog signals containing actual drawbar pull and speed in the remote control user interface. Constant slope mode and trailer simulation-Menu based calculation of drawbar pull with user-editable slope, towing vehicle and trailer parameters (e.g. drag coefficient, towing vehicle weight) Hill profile mode -Menu based hill profile input, realtime drawbar pull control with user-editable towing vehicle and trailer parameters (e.g., drag coefficient, towing vehicle weight). Dynamic trailer simulation -Simulation of mass inertia of the trailer via drawbar pull control during acceleration and deceleration. Online slope correction -Actual slope is detected via Sensors and compensated by drawbar pull control for slope independent drawbar pull. Dead weight trailer simulation -Simulated increase of trailer mass via drawbar pull control during acceleration, deceleration and downward force due to actual slope GPS-measurement for actual speed, displayed and loggable via remote control. 2 spare wheels and wheel retaining mounts inside the chassis, covered by the hood. Transport platform for transport damage prevention. For transportation duties the towing dynamometer will be tied down on the platform, forklift suited lifting points on both sides. Additional control regarding actual towing vehicle values (e.g., fuel injection rate) on request. **Documentation** User manual including brief instruction and maintenance interval in english or german language. Wear and spare part list. These are mainly available from automotive suppliers. Electric wiring diagrame



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